

Rigidity results of Alexandrov type

based on joint works with DORIN BUCUR (U. Savoie)

1. Alexandrov Theorem - moving planes
2. Link with the isoperimetric inequality - rigidity for sets with finite perimeter
3. Interplay with PDE's
4. Rigidity for k -dense domains

5. A new rigidity problem.
6. Link with Riesz rearrangement inequality
7. Fractional rigidity
8. Rigidity for α -critical sets - new moving planes

9. Rigidity for general kernels
10. Rigidity for polygons.

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1. Alexandrov Theorem (1958)

Theorem.

Let $\Omega \subseteq \mathbb{R}^m$ be a bounded connected domain, with $\partial\Omega \in C^2$.

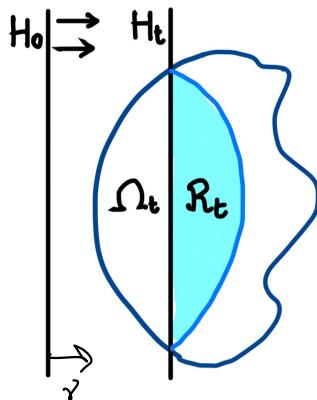
Then

$$H_\Omega(x) = c > 0 \quad \forall x \in \partial\Omega \iff \Omega \text{ is a ball}$$

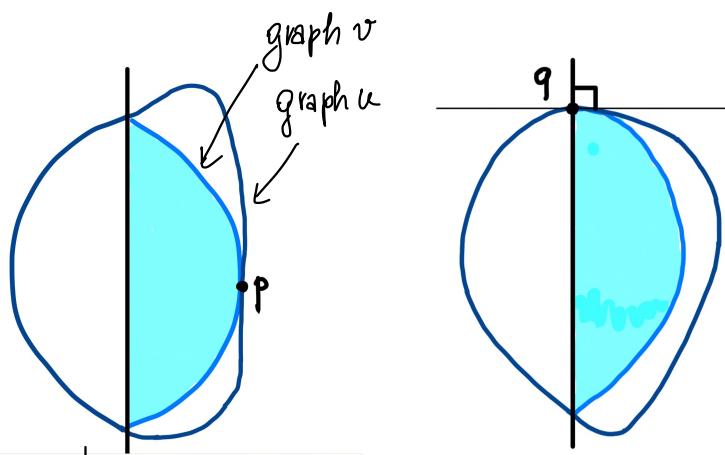
- false if Ω is not bounded (Ω half space)
- false if Ω is not connected ($\Omega = B_1 \sqcup B_2$)
- ??? if Ω is not C^2 (H_Ω ???)
- false if $\partial\Omega$ not embedded (Wentzels)

Proof. By moving planes

Start



Stop.



1) Interior tangency

2) Orthogonality

Goal: $w := u - v$, $\boxed{w \equiv 0 \text{ near } p/q}$

We know: $w(p) = 0$, $w \leq 0 \text{ near } p$.

$$H_2 = \frac{1}{n-1} \operatorname{div} \left(\frac{\nabla u}{\sqrt{1+|\nabla u|^2}} \right) = \frac{1}{n-1} \left(\frac{\Delta u}{\sqrt{1+|\nabla u|^2}} - \frac{\nabla^2 u \cdot \nabla u \cdot \nabla u}{(1+|\nabla u|^2)^{3/2}} \right)$$

↓

$$\sum_{i,j} a_{ij}(x) \partial_{ij}^2 w + \sum_k b_k(x) \partial_k w = 0 \quad \forall w \in U(p/q)$$

uniformly elliptic with bounded coefficients

- 1) Interior tangency : w takes its max at an interior point
 \Rightarrow by the STRONG MAX PRINCIPLE, $w=0$ near p

- 2) Orthogonality : w takes its max at a boundary point

\Rightarrow by HOPF BOUNDARY POINT LEMMA

$\frac{\partial w}{\partial \nu}(q) < 0 \quad \leftarrow$ ruled out by orthogonality

$w = 0 \quad \text{near } q$

Conclusion : Ω has a plane of symmetry
 in every direction.

2. Link with the isoperimetric inequality -
rigidity for sets with finite perimeter

Let Ω be as in Alexandrov Thm.

$$\mathcal{Q}(\Omega) := \frac{\text{Per}(\Omega)}{|\Omega|^{\frac{n-1}{n}}} \quad \text{isoperimetric quotient}$$

Def. Ω is a critical set for \mathcal{Q} if

$$\left. \frac{d}{dt} \mathcal{Q}(\Omega_t) \right|_{t=0} = 0 \quad \forall \Omega_t = \phi_t(\Omega) \text{ perturbation of } \Omega \\ \phi_t(x) = x + tX(x) + o(t), \quad X \in C_c^1(\mathbb{R}^n; \mathbb{R}^n)$$

Remark: Ω is a critical set for $\mathcal{Q} \iff H_\Omega(x) = c \quad \forall x \in \partial\Omega$
 remains true for sets of finite perimeter

$$\begin{aligned} \left. \frac{d}{dt} |\Omega_t| \right|_{t=0} &= \int_{\Omega} \text{div} X \stackrel{(1)}{=} \int_{\partial\Omega} X \cdot \nu_\Omega \, dH^{n-1} \quad \forall X \in C_c^1(\mathbb{R}^n; \mathbb{R}^n) \\ \left. \frac{d}{dt} \text{Per}(\Omega_t) \right|_{t=0} &= \int_{\Omega} \underbrace{\text{div}_{\nu_\Omega} X}_{\text{div } X - D_\Omega \cdot \nabla X[\nu_\Omega]} \stackrel{(2)}{=} \int_{\Omega} H_\Omega X \cdot \nu_\Omega \, dH^{n-1} \\ &\quad L_{loc}^1(\partial\Omega; dH^{n-1}) \end{aligned}$$

$$\forall X \in C_c^1(\mathbb{R}^n; \mathbb{R}^n).$$

Question: Does Alexandrov Thm hold for sets with finite perimeter?

Thm. [Delgadino-Maggi, Anal & PDE's 2019]

Among sets with finite vol and finite per,

the unique critical sets for Ω

(or sets with constant distributional mean curvature)

are finite unions of equal balls.

Idea of the proof

HEINZEN - KARCHER INEQUALITY : $\Omega \subset \mathbb{C}^n$ with $H_2 > 0$

$$|\Omega| \leq \frac{n-1}{n} \int_{\partial\Omega} \frac{1}{H_2} dH^{n-1}, \text{ with } = \Leftrightarrow \Omega = B$$

$$H_2 = c \text{ on } \partial\Omega \Rightarrow \int_{\partial\Omega} H_2 x \cdot v = \int_{\partial\Omega} c x \cdot v \Rightarrow c = \frac{n-1}{n} \frac{\text{Per}(\Omega)}{|\Omega|}$$

\parallel
 $(n-1) \text{Per}(\Omega)$ $c n |\Omega|$



3. Interplay with PDE's

- Elliptic PDE's

Thm. [Serrin, ARMA 1971]

Consider the overdetermined problem:

$$\begin{cases} -\Delta u = 1 & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \\ |\nabla u| = e & \text{on } \partial\Omega \end{cases}$$

\exists solution $\Leftrightarrow \Omega = B$

- Parabolic PDE's

Thm. [Magnanini-Jakaguchi, Ann. of Math 2002]

Consider hatzoh ball soup problem:

$$\begin{cases} u_t - \Delta u = 0 & \text{in } \Omega \times (0, +\infty) \\ u = 0 & \text{in } \Omega \times \{0\} \\ u = 1 & \text{on } \partial\Omega \times (0, +\infty) \end{cases}$$

The isothermic surfaces $\{u(\cdot, t) = \text{const}\}$ are stationary

$\Rightarrow \Omega = B$

4

Thm. [Magnanini - Prejapati - Sakaguchi, TAMS 2006]

Consider the problem:

$$\begin{cases} u_t - \Delta u = 0 & \text{in } \mathbb{R}^m \times (0, +\infty) \\ u(x, 0) = \chi_{\Omega}(x) & \text{in } \mathbb{R}^m \end{cases}$$

$\partial\Omega$ is stationary isothermic $\Leftrightarrow \Omega$ is B -dense
 $(u(x, t) = \alpha(t) \quad \forall x \in \partial\Omega, \forall t \in (0, +\infty))$

Def. Ω is B -dense $\Leftrightarrow \forall r > 0 \exists c = c(r)$ such that
 $|\Omega \cap B_r(x)| = c(r) \quad \forall x \in \partial\Omega$

Question: let Ω be bounded (measurable)

Ω is B -dense $\stackrel{??}{\Rightarrow} \Omega = B$

as $r \rightarrow 0^+$

$$\bullet |\Omega \cap B_r(x)| \stackrel{\downarrow}{=} \frac{1}{2} \omega_m r^m - \gamma_m H_\nu(x) r^{m+1} + o(r^{m+1})$$

[Hulin - Troyanov, Amer. J. Math., 2003]

4. Rigidity for K-dense domains

Let Ω be a set of finite Lebesgue measure,
let K be a convex body with $0 \in \text{int}(K)$

Def. Ω is K -dense if $|\Omega \cap (x+rK)| = c(r) \quad \forall x \in \partial\Omega, \forall r > 0$

Question: what can be said about Ω (and K) ?

Thm. [Mazzonini-Marini, Proc. Roy Soc Edinburgh 2016]

Ω is K -dense $\Leftrightarrow \Omega$ and K are homothetic ellipsoids
(In particular, if K is a ball, Ω is a ball).

Idea of the proof.

$$|\Omega \cap (x+rK)| = |\Omega| + \underbrace{\mathbb{W}(x)}_{\substack{\uparrow \\ \Omega, K}} (r_{\Omega, K}(x) - r)^{\frac{n+1}{2}} + o(\dots)$$

$$\text{as } r \rightarrow r_{\Omega, K}(x) = \inf \{r > 0 : \Omega \subseteq x+rK\}$$

$$\mathbb{W}(x) = \text{const} \Leftrightarrow \begin{cases} \Omega \text{ and } K \text{ are homothetic} \\ G_K = e^{\Phi_K^{\frac{n+1}{2}}} \Rightarrow K \text{ is an ellipsoid.} \end{cases}$$

\uparrow \uparrow Petty Thm.
 gaussian curvature support function



5. A new rigidity problem.

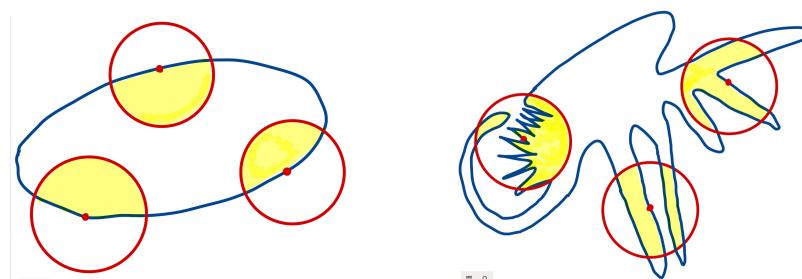
Fix $r > 0$.

Characterize measurable sets $\Omega \subseteq \mathbb{R}^m$, with $|\Omega| < +\infty$, such that

$$\boxed{|\Omega \cap B_r(x)| = c \quad \forall x \in \partial^* \Omega} \quad \leftarrow \Omega \text{ is "r-critical"}$$

$$(\partial^* \Omega)_{n1} := \left\{ x \in \mathbb{R}^m : \limsup_{r \rightarrow 0} \frac{|\Omega \cap B_r(x)|}{r^n} > 0, \limsup_{r \rightarrow 0} \frac{|\Omega \cap B_r^c(x)|}{r^n} > 0 \right\}$$

$\partial \Omega$



Historical note (on the origins of the problem)

- [Cimmino, Rend. Accad. Naz. Lincei 1932]:

Is it possible to characterize smooth surfaces $\Gamma = \partial\Omega$ in \mathbb{R}^3 such that

$$H^2(\Omega \cap \partial B_r(x)) = 2\pi r^2 \quad \forall x \in \Gamma, \quad \forall r > 0 \text{ suff. small}$$

- [Nitsche, Analysis 1995]

The only smooth surfaces with this property are:
the plane and the right helicoid

More references (on the noncompact case)

- [Meeks - Rosenberg, Ann. of Math. 2005]

The plane and the right helicoid are the unique
simply connected minimal surfaces embedded in \mathbb{R}^3

- [Kapouleas, Ann. of Math. 1990]

A general construction of CMC surfaces in \mathbb{R}^3
(many noncompact examples are embedded!)

Back to our problem:

Characterize measurable sets $\Omega \subseteq \mathbb{R}^n$, with $|L\Omega| < +\infty$, such that

$$\boxed{|L\Omega \cap B_r(x)| = c \quad \forall x \in \partial^* \Omega} \quad \leftarrow \Omega \text{ is "r-critical"}$$

Generalized version:

$$|L\Omega \cap B_r(x)| = \int_{\Omega} \chi_{B_r(x)}(y) dy = \int_{\Omega} \chi_{B_r(0)}(x-y) dy$$

$\chi_{B_r(0)}$ ms $h: \mathbb{R}^n \rightarrow \mathbb{R}_+$ radially symmetric

Characterize measurable sets $\Omega \subseteq \mathbb{R}^n$ such that

$$\boxed{\int_{\Omega} h(x-y) dy = c \quad \forall x \in \partial^* \Omega} \quad \leftarrow \Omega \text{ is "h-critical"}$$

6. Link with Riesz rearrangement inequality

12

- Given $h: \mathbb{R}^n \rightarrow \mathbb{R}_+$ radially symmetric

$$\underbrace{\iint_{\Omega \times \Omega} h(x-y) dx dy}_{J_h(\Omega)} \leq \iint_{\Omega^* \times \Omega^*} h(x-y) dx dy$$

\Downarrow

ball with $|\Omega^*| = |\Omega|$

- Ω h -critical $\Leftrightarrow \frac{d}{dt} J_h(\Omega_t) \Big|_{t=0} = 0 \quad \forall \Omega_t = \phi_t(\Omega)$ volume preserving
-

Nonlocal perspective:

$$J_h(\Omega) = e - \underbrace{\iint_{\Omega \times \Omega^c} h(x-y) dx dy}_{h\text{-Per}(\Omega)}$$

- Riesz inequality $\rightsquigarrow h\text{-Per}(\Omega) \geq h\text{-Per}(\Omega^*)$

$$\begin{aligned} \iint_{\Omega} h(x-y) dy &\rightsquigarrow \text{nonlocal } h\text{-mean curvature} \\ \left(\int_{\mathbb{R}^n} h(x-y) [\chi_{\Omega^c}(y) - \chi_{\Omega}(y)] dy \right) \end{aligned}$$

[Bourgain - Brézis - Mironescu, Optimal Control & PDES, 2001]

[Maton - Rossi - Toledo, Birkhäuser 2019]

4. Fractional rigidity $\left(h(x) = \frac{1}{|x|^{n+2s}}, s \in (0, \frac{1}{2}) \right)$ ✓¹³

$$P_{\text{Fr}}(\Omega) = \int_{\Omega} \int_{\Omega^c} \frac{1}{|x-y|^{n+2s}} dx dy \quad (\Omega \subset \mathbb{C}^{1,\alpha}, \alpha > 2s)$$

$$H_s(\Omega) = \int_{\mathbb{R}^n} \frac{\chi_{\Omega^c}(y) - \chi_{\Omega}(y)}{|x-y|^{n+2s}} dy$$

[Caffarelli - Souganidis, CPAM 2008]

[Caffarelli - Roquejoffre - Jain, CPAM 2010]

- Fractional isoperimetric inequality:

$$P_{\text{Fr}}(\Omega) \geq P_{\text{Fr}}(\Omega^*) \quad [\text{Frank-Lieroinger, JFA 2008}]$$

- Fractional Alexandrov Theorem:

Ω bounded open set of class $C^{1,\alpha}$ with $H_s = c$ on $\partial\Omega \Rightarrow \Omega = B$

[Cabré - Fall - Jola Morales - Weth, J. Reine Angew. Math. 2018]

[Cirillo - Figalli - Maggi - Novaga, " " " "]

→ no bubbling!

→ proof by moving planes.

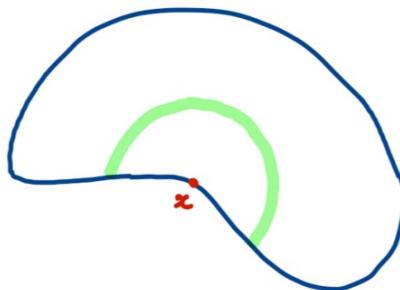
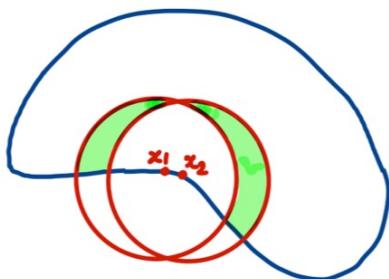
8. Rigidity for r-critical sets

The Kernel $h = \chi_{B_r(0)}$ is:

- BOUNDED
- COMPACTLY SUPPORTED
- DISCONTINUOUS

Def. A measurable set Ω is r -nondegenerate if

$$\inf_{x_1, x_2 \in \partial^* \Omega} \frac{|\Omega \cap (B_r(x_1) \Delta B_r(x_2))|}{|x_1 - x_2|} > 0$$



Lemma :

Ω open connected $\Rightarrow \Omega$ r -nondegenerate $\forall r < \text{diam } \Omega$

- same for Ω of finite perimeter indecomposable
- if $\Omega = \bigsqcup_i \Omega_i$ $\Rightarrow r \inf_i (\text{diam } \Omega_i)$
 \uparrow
 components of Ω

Thm. [Buehr-F., ArXiv Preprint 2021]

Let $r > 0$, and let $\Omega \subseteq \mathbb{R}^n$ be measurable with $|\Omega| < +\infty$.

Assume Ω is r -critical and r -nondegenerate.

Then Ω is equivalent to a finite union of equal balls, of radius $R > \frac{r}{2}$, at mutual distance larger than or equal to r .

"Regular" cases:

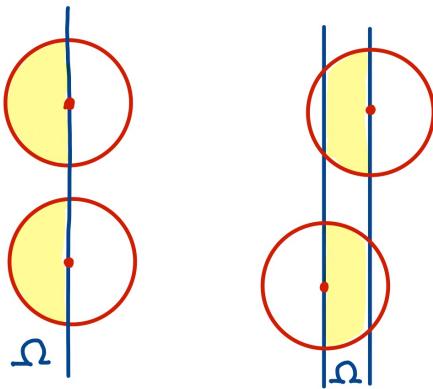
- Ω open connected set, with $|\Omega| < +\infty$
 Ω r -critical, $r < \text{diam } \Omega \Rightarrow \Omega = B$.
- Ω of finite perimeter immeasurable, with $|\Omega| < +\infty$
 Ω r -critical, $r < \text{diam } \Omega \Rightarrow \Omega = B$.

Remark : The same result holds if $B \rightsquigarrow E$ ellipsoid

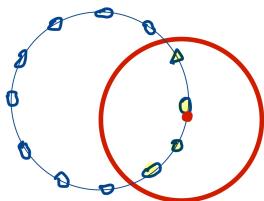
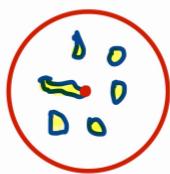
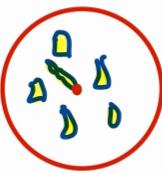
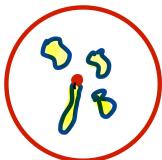
16

Sets escaping from rigidity (though r-critical)

- Sets of infinite measure



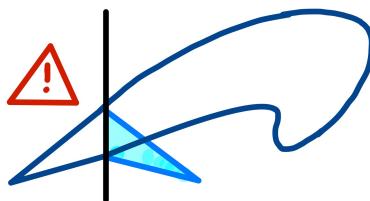
- r-degenerate sets



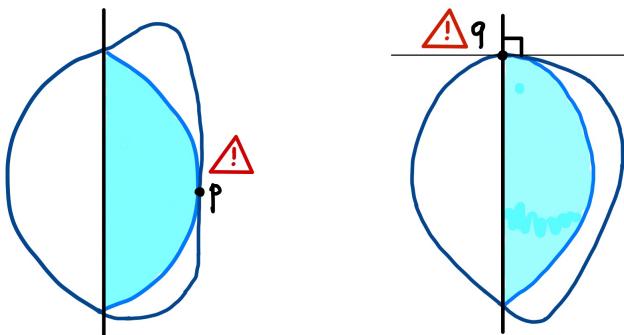
Proof:

Classical moving planes fail

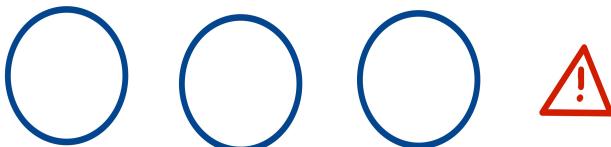
- Start:



- Stop:

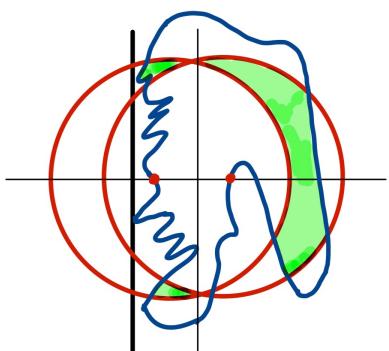
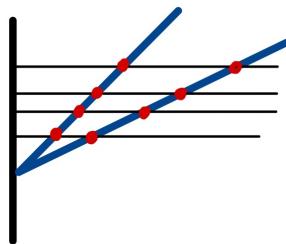


- Conclusion:



New moving planes

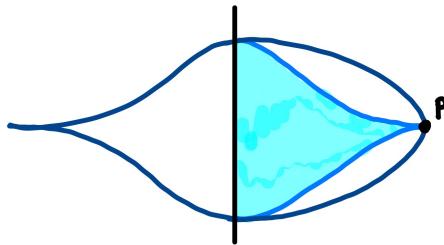
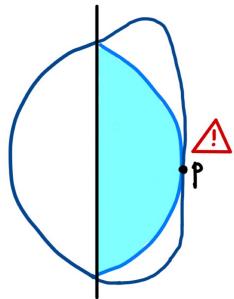
- Start: Under the hypotheses of the Thm, for $t \ll 1$
 $R_t \subseteq \Omega$ and $\Omega_t \cup R_t$ is Steiner symmetric about H_t
(By contradiction)



• Stop:

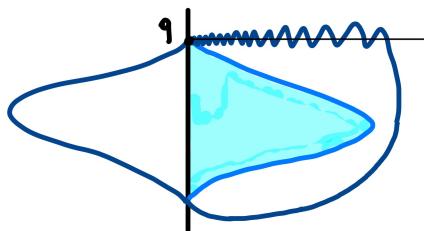
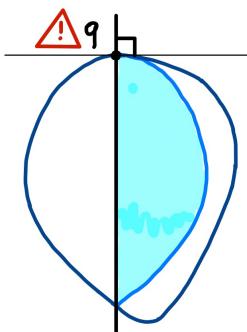
1) Interior tangency \Rightarrow Away contact

$$p \in (\overline{\partial^* Q} \cap \overline{\partial^* R_t}) \setminus H_t$$



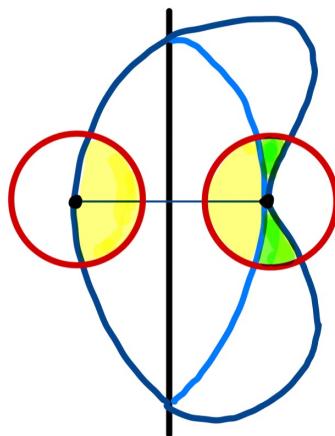
2) Orthogonality \Rightarrow Close contact

$$q = \lim_n q_m^1 = \lim_n q_m^2, \quad \Pi_{H_t}(q_m^1) = \Pi_{H_t}(q_m^2)$$



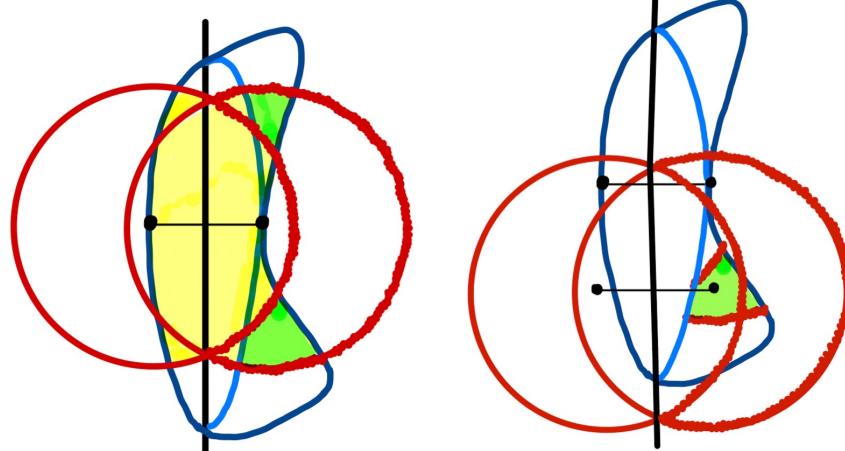
i) Away contact \Rightarrow local symmetry

Easy situation: $B_r(p) \cap B_r(p') = \emptyset$ (use r-criticality)



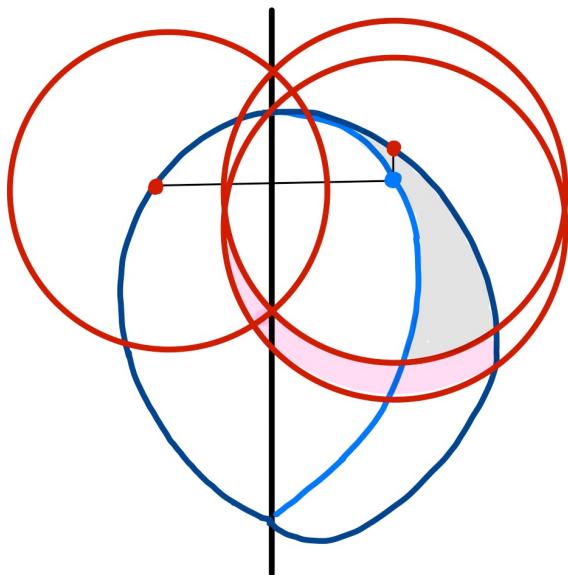
More delicate situation: $B_r(p) \cap B_r(p') \neq \emptyset$

use symmetry inside r-moons and a ping-pong game



2) Close contact: not possible without away contact

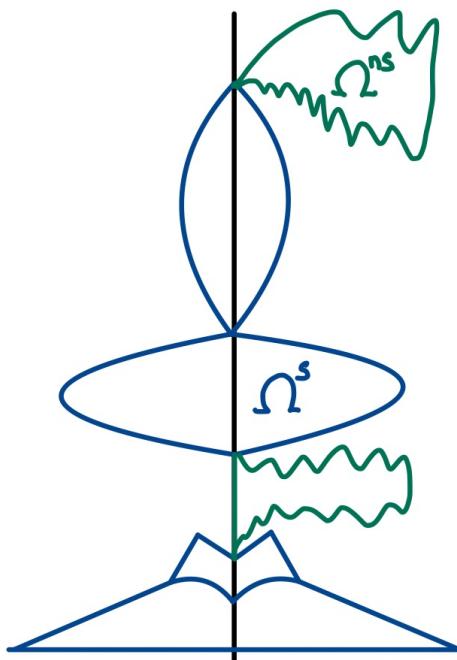
(Based on a local analysis exploiting monogeneracy)



• Conclusion

✓

- Under some "connectedness" hyp $\Rightarrow \Omega = B$
- In general: $\Omega = \Omega^s \cup \Omega^{ns}$, with Ω^s OPEN \Rightarrow
 - Ω^s finite union of balls
 - Ω^{ns} Lebesgue negligible



9. Rigidity for general Kernels

Let $h \in L^1_{loc}(\mathbb{R}^m; \mathbb{R}_+)$ radially symmetric nonincreasing.

Let $\Omega \subseteq \mathbb{R}^m$ be measurable, with $|\Omega| < +\infty$.

$$|\Omega \cap B_r(x)| = e^{-\int_{\Omega} h dy} \quad \forall x \in \partial^* \Omega$$



$$\int_{\Omega} h(x-y) dy = e^{-\int_{\Omega} h dy} \quad \forall x \in \partial^* \Omega$$

Ω is h -critical

$$\inf_{x_1, x_2 \in \partial^* \Omega} \frac{|\Omega \cap (B_{r_1}(x_1) \Delta B_{r_2}(x_2))|}{|x_1 - x_2|} > 0$$



$$\inf_{x_1, x_2 \in \partial^* \Omega} \int_{\Omega} \frac{|h(x_1-y) - h(x_2-y)| dy}{|x_1 - x_2|} > 0$$

Ω is h -nondegenerate

Remark:

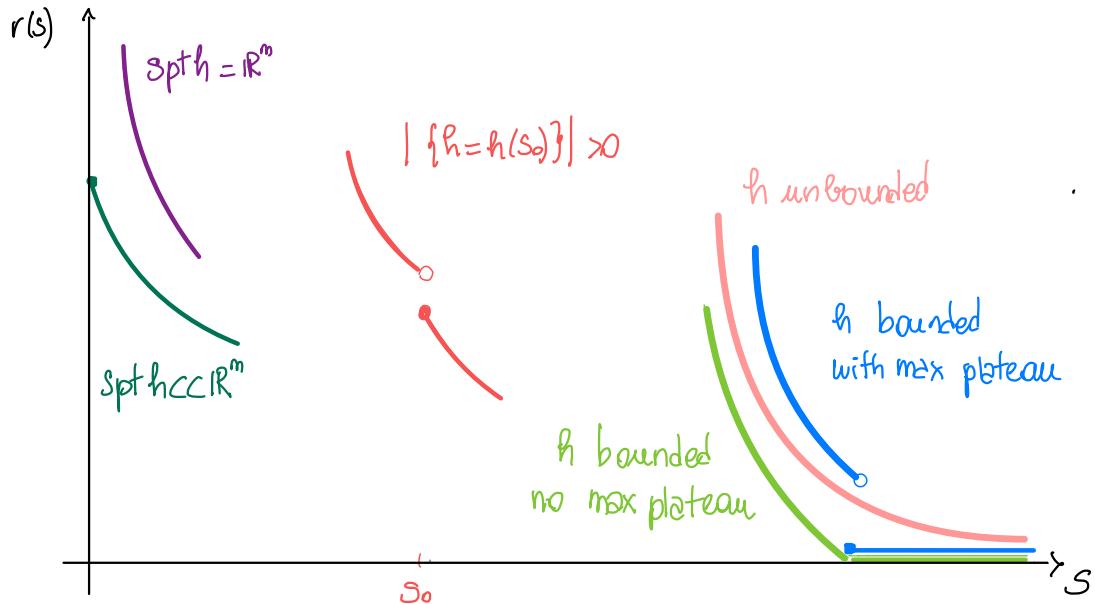
$$\int_{-\infty}^{\infty} h(x-y) dy = \int_0^{+\infty} |\Omega \cap B_{r(s)}(x)| ds, \quad \text{where}$$

$$\boxed{B_{r(s)}(0) = \{h > s\}}$$

If $\Psi: \mathbb{R}_+ \rightarrow \mathbb{R}_+$ is defined by $\Psi(x) := h(|x|)$

$r(s) = \mathcal{L}^1(\{x \in \mathbb{R}^m : \Psi(x) > s\})$ DISTRIBUTION FUNCTION OF Ψ

Properties of the map $s \mapsto r(s) = \mathcal{L}^1(\{\varphi > s\})$



- monotone decreasing, with $\sup_{(0,+\infty)} r(s) = r(0^+) = \mathcal{L}^1(\{s \in \text{spt } \varphi\})$
- right continuous
continuous at $s=s_0 \Leftrightarrow \mathcal{L}^1(\{\varphi = \varphi(s_0)\}) = 0$
- $r(s) = 0 \quad \forall s \geq \text{ess sup } \varphi$
- $\gamma := \mathcal{L}^1(\{\varphi = \text{ess sup } \varphi\})$
- $\delta := \begin{cases} \sup \{s : r(s) > \text{diam } \Omega\} & \text{if } r(0) > \text{diam } \Omega \\ 0 & \text{if } r(0) \leq \text{diam } \Omega \end{cases}$
- $r(\delta) < \text{diam } \Omega \Leftrightarrow \begin{cases} \mathcal{L}^1(\{\varphi = \varphi(\text{diam } \Omega)\}) > 0 \\ r(0) < \text{diam } \Omega \end{cases}$

Theorem [Buer - F., ArXiv Preprint 2022]

Let $\Omega \subseteq \mathbb{R}^n$ with $|\Omega| < +\infty$ be h-critical and h-nondegenerate

Assume that $\int_1^{+\infty} r(s)^{n-1} ds < +\infty \quad (*)$

Then Ω is a finite union of balls B_i of the same radius R .

Moreover: $R > \frac{\eta}{2}$ and $\text{dist}(B_i, B_j) \geq r(\emptyset)$

On the assumptions

- About condition (*) (improved integrability)

$$\int_K h = \int_0^{+\infty} |K \cap B_{r(s)}| ds \Rightarrow h \in L^1_{loc} \text{ provided } \int_1^{+\infty} r(s)^n ds < +\infty$$
- Lemma (about mondegeneracy)
 - Ω open connected, $r < \text{diam } \Omega \Rightarrow \Omega$ r-nondegenerate
 - $\Rightarrow \Omega$ open connected, $\eta < \text{diam } \Omega \Rightarrow \Omega$ h-nondegenerate

On the geometric impact of the Kernel

- R is bounded from below $\Rightarrow \eta > 0$ (maximal plateau)
- Multiple balls are allowed $\Rightarrow r(\emptyset) < \text{diam } \Omega$

Example 1

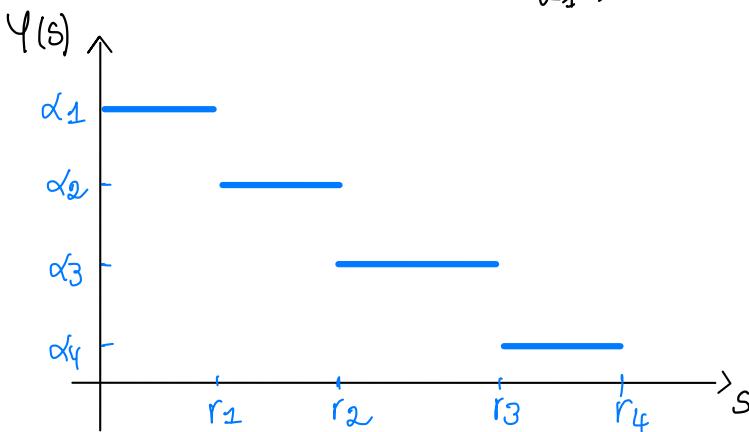
$$h(x) = \frac{1}{|x|^{\alpha}}$$

improved integrability OK for $\alpha < n-1$

- $\eta = 0 \Rightarrow R > 0$
- $r(s) = +\infty \Rightarrow$ multiple balls not allowed.

Example 2

$$h(x) = \sum_{i=1}^N \alpha_i \chi_{B_{r_i}(0) \setminus B_{r_{i-1}}(0)} \quad \begin{matrix} \alpha_1 > \dots > \alpha_N \\ r_1 < \dots < r_N \end{matrix}$$



improved integrability OK (since h is bounded)

- $\eta = r_1 \Rightarrow R > \frac{r_1}{2}$
- $r(s) \in \{r_1, \dots, r_N\} \Rightarrow$ multiple balls allowed

On the relationship with Burchard's work

[Burchard, Ann of Math 1996]

- Characterization of equality cases in general Riesz inequality:

$$\int_{\mathbb{R}^n} \int_{\mathbb{R}^n} f(x) g(y) h(x-y) dx dy \leq \int_{\mathbb{R}^n} \int_{\mathbb{R}^n} f^*(x) g^*(y) h^*(x-y) dx dy$$

$$(f=g=X_\Omega, h=h^* \Rightarrow \int_{\Omega} \int_{\Omega} h(x-y) dx dy \leq \int_{\Omega^*} \int_{\Omega^*} h(x-y) dx dy)$$

→ Case of characteristic functions: $f=X_{\Omega_1}, g=X_{\Omega_2}, h=X_{\Omega_3}$

$\Rightarrow \Omega_i$ are balls (homothetic ellipsoids), or homothetic convex bodies

In particular: if Ω_3 is a ball $\Rightarrow \Omega_1, \Omega_2$ are balls

→ Case of arbitrary functions:

Almost all level sets must produce equality (hard to check!)

In particular: if $f=g=X_\Omega$,

only for h STRICTLY DECREASING, it follows that Ω is a ball

\Rightarrow for h non strictly decreasing, our result gives some NEW INFORMATION about possible maximizers (CRITICAL SETS)

even though the ADDITIONAL HYPOTHESES of improved integrability and h -monotonicity.

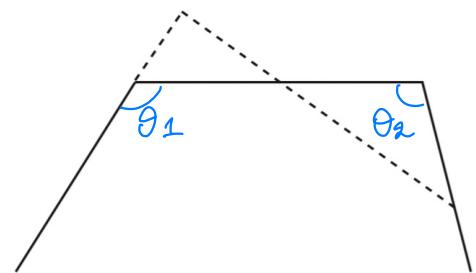
10. Rigidity for polygons

28

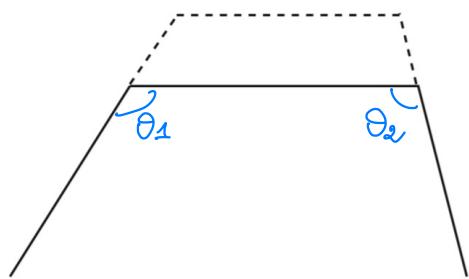
- Polygonal isoperimetric inequality $Q(P) = \frac{|OP|}{|P|^{\frac{1}{2}}}$
- $Q(P) \geq Q(P_N^*)$ $\forall P \in \mathcal{O}_N = \{N\text{-gons}\}$
 \uparrow
 regular N -gon

Moreover, P_N^* is the unique critical N -gon, namely the unique N -gon such that

$$\frac{d}{dt} Q(P_t) \Big|_{t=0} = 0 \quad \text{for the following perturbations } \{P_t\}:$$



ROTATION AROUND MID-POINT



PARALLEL MOVEMENT

$$\begin{cases} \frac{d}{dt} |OP_t| \Big|_{t=0} = \frac{1}{2} (f(\theta_1) - f(\theta_2)) \\ \frac{d}{dt} |P_t| \Big|_{t=0} = 0 \end{cases}$$

$$\begin{cases} \frac{d}{dt} |OP_t| \Big|_{t=0} = f(\theta_1) + f(\theta_2) \\ \frac{d}{dt} |P_t| \Big|_{t=0} = l \end{cases}$$

$$(f(\theta) = \sin \theta + \frac{1}{\sin \theta})$$

✓29

Question : what happens in the polygonal setting
when dealing with Finsz type energies (or nonlocal perimeters) ?

$$J_h(P) = \iint_{P \times P} h(x-y) dx dy \quad P \in \mathcal{P}_N = \{N\text{-gons}\}$$

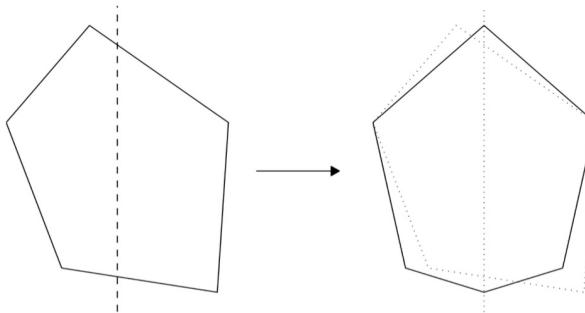
① Is P_N^* a minimizer under area constraint ?

???

$$J_h(P) \leq J_h(P_N^*) \quad \forall P \in \mathcal{P}_N = \{N\text{-gons}\}, |P| = |P_N^*|$$

CURRENTLY OPEN, EXCEPT FOR $N=3, 4$ (true)

The proof is based on Steiner symmetrization



$N \geq 5 \Rightarrow$
proof fails!

[Bonacini - Cristofori - Topaloglu , JGA 2022]

[Polya - Szego , Isop. inequalities in math. Physics 1951]

[Brascamp - Rieb - Ruttinger , JFA 1974]

② Is P_N^* critical for J_h under area constraint? YES
 Is it unique ??? (\rightarrow answer to question ①!)

CURRENTLY OPEN, EXCEPT FOR $N=3, 4$ (true)

Setting $v_p(x) = \int_P h(x-y) dy$,

the stationarity conditions read:

ROTATION AROUND MID-POINT

$$(*) \int_{\overline{P_i M_i}} v_p(x) |x - M_i| dH^1 = \int_{\overline{P_{i+1} M_i}} v_p(x) |x - M_i| dH^1 \quad \forall i=1, \dots, N$$

mid-point of $\overline{P_i P_{i+1}}$

PARALLEL MOVEVENT independent of i

$$(**) \int_{\overline{P_i P_{i+1}}} v_p(x) dH^1 = \downarrow H^1(\overline{P_i P_{i+1}}) \quad \forall i=1, \dots, N$$

Thm [Bouzeini-Cristofoli-Topaloglu, JGA 2022]

The regular triangle/square is the unique

triangle/quadrilateral satisfying (*) - (**).

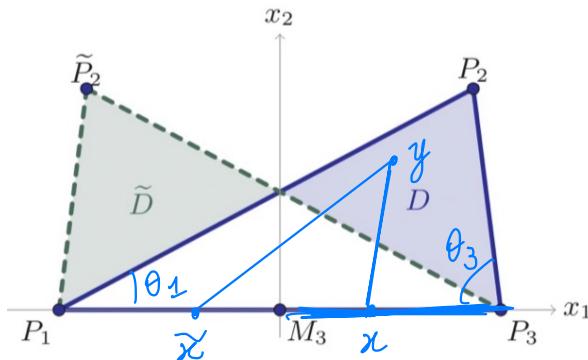
(under some regularity hypotheses on the kernel)

Proof by reflection ($N=3$)

3

ref. [F. - Velichkov , Trans AMS 2019]

By contradiction



$$\varphi_{\tilde{P}}(x) - \varphi_P(x) = \int_{\tilde{P}} h(x-y) dy - \int_P h(x-y) dy$$

$$= \int_D h(x-y) dy - \int_D h(x-y) dy$$

$$= \int_D [h(\tilde{x}-y) - h(x-y)] dy < 0$$

¶

$\uparrow h$ strictly
decreasing

$$\int_{M_2 P_3} \varphi_{\tilde{P}}(x) |x-M_3| < \int_{M_3 P_3} \varphi_P(x) |x-M_3|$$

$$\int_{P_1 M_3} \varphi_{\tilde{P}}(x) |x-M_3|$$

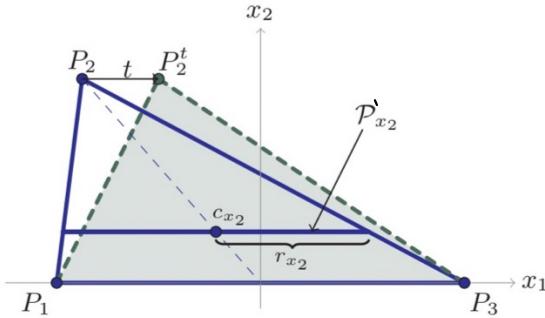
AGAINST (*)

□

Proof by slices ($N=3$)

cf. [Carrillo-Hittmeier-Volzone-Yar, Inventiones 2019]

By contradiction:



$$\begin{aligned}
 J_h(P) &= \iint_{P \cap P} h(x-y) dx dy \\
 &= \int_R \int_R \underbrace{I_{h_\ell}(P^{x_2}, P^{y_2})}_{\text{!!}} dx_2 dy_2 \\
 &\quad \int_{P^{x_2}} \int_{P^{y_2}} h_\ell(x_1-y_1) dx_1 dy_1
 \end{aligned}$$

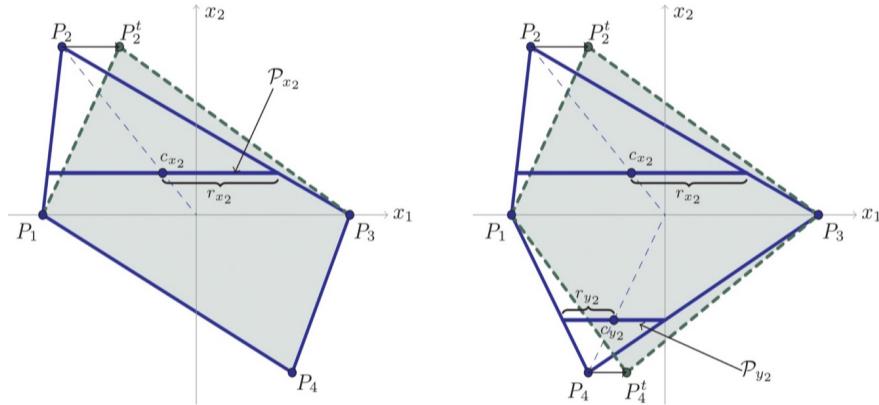
$$\begin{cases} h_\ell(r) = h(\sqrt{r_1^2 + r_2^2}) \\ \ell = |x_2 - y_2| \end{cases}$$

$$\left. \frac{d}{dt} J_h(P_t) \right|_{t=0} = \int_R \int_R \underbrace{\frac{d}{dt} I_{h_\ell}(P_t^{x_2}, P_t^{y_2})}_{\text{VI}} dx_2 dy_2 \geq C' > 0$$

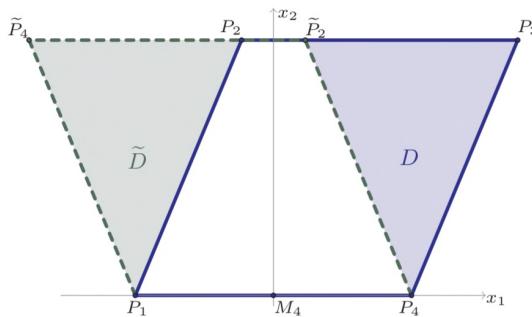
$$C' \min \{r_{x_2}, r_{y_2}\} |c_{x_2} - c_{y_2}| |x_2 - y_2|$$

Proof (N=4)

By slices \Rightarrow rhombus



By reflection \Rightarrow square



Open problems

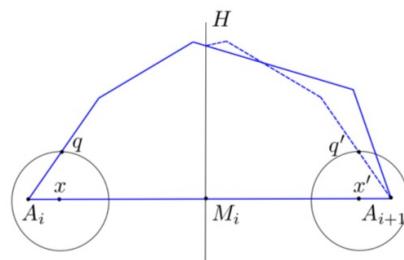
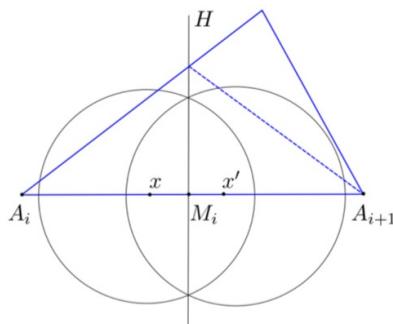
- ① Prove rigidity for more general kernels, in particular not satisfying improved integrability
- ② Prove rigidity for polygons when $\mathbf{h} = \mathbf{1}_{B_r(0)}$:

Given $r > 0$, the regular N -gon is the unique N -gon such that

$$(*) \quad \int_{A_i}^{A_{i+1}} |P_n \cap B_r(x)| dH^1(x) = c H^1(A_i \overline{A_{i+1}}) \quad \forall i=1,\dots,N$$

$$(**) \quad \int_{A_i}^{M_i} |P_n \cap B_r(x)| |x - M_i| dH^1 = \int_{M_i}^{A_{i+1}} |P_n \cap B_r(x)| |x - M_i| dH^1 \quad \forall i=1,\dots,N$$

- True for $N=3$
- True for every N if r is small enough



- ③ Prove some stability result for sets with "almost constant" nonlocal mean curvature.

Stability of Alexandrov type results

- [Ciraolo-Maggi CPAM 2017, Ciraolo-Vettoni JEMS 2018]
STABILITY OF CLASSICAL ALEXANDROV
- [Ciraolo- Figalli-Maggi-Novaga, J. Reine Angew. Math 2018]
STABILITY IN THE FRACTIONAL CASE

Quantitative Riesz type inequalities

- [Christ, ArXiv Preprint 2017]
- [Frank-Lieb, ArXiv Preprint 2019 & Ann. SNS Pisa 2021]

Many Thanks

for your attention !

→ For any comment/question, e-mail to:

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