

# Around Bezout inequalities for mixed volumes

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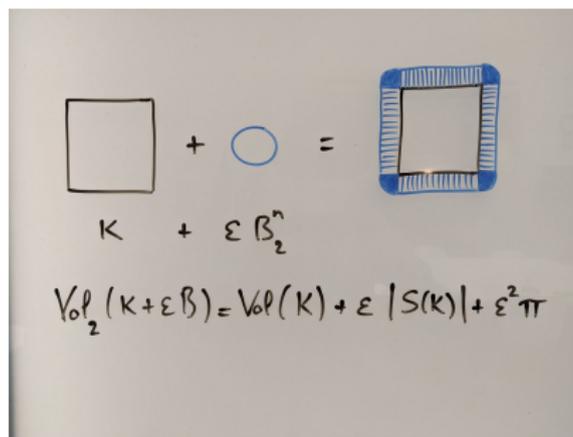
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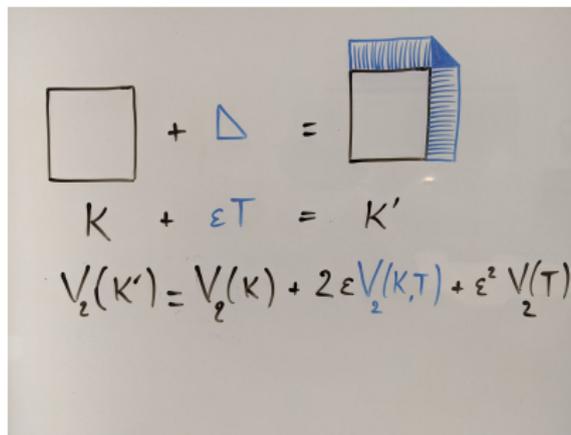
AGA Seminar - Zoom

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## Steiner polynomial

For any  $K \in \mathcal{K}_n$ , there exists non-negative  $\{v_k; 0 \leq k \leq n\}$  such that :  $\forall \varepsilon > 0$ ,  
 $Vol_n(K + \varepsilon B_2^n) = \sum_{k=0}^n \binom{n}{k} v_k \varepsilon^k$ .





$Vol_n(K + \varepsilon T)$  is also a polynomial in  $\varepsilon$  (even if  $T \in \mathcal{K}_n$  is not a ball).

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Let  $K, L \in \mathcal{K}_n$ , let  $\lambda, \mu \geq 0$ . Then  $\text{Vol}_n(\lambda K + \mu L)$  is a polynomial in  $(\lambda, \mu)$  :

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where  $v_k = V_n(K[k], L[n-k]) = V_n(K, \dots, K, L, \dots, L)$  are called **mixed volumes**.

- Let  $K, L \in \mathcal{K}_n$ ,  $\lambda, \mu \geq 0$ . . Then  $Vol_n(\lambda K + \mu L) = \sum_{k=0}^n \binom{n}{k} v_k \lambda^k \mu^{n-k}$
- Let  $K_1, \dots, K_m \in \mathcal{K}_n$ . Let  $\lambda_1, \dots, \lambda_m \geq 0$ . Then :

$$Vol_n(\lambda_1 K_1 + \dots + \lambda_m K_m) = \sum_{\substack{a=(a_1, \dots, a_m) \\ |a|=n}} \binom{n}{a} v_a \lambda_1^{a_1} \dots \lambda_m^{a_m}$$

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- $V_n : \mathcal{K}_n^n \rightarrow [0, +\infty)$  is a **multilinear**, **continuous** functional.

Let  $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$  be an affine transform. Then :

$$V_n(TK_1, \dots, TK_n) = |\det(T)| V_n(K_1, \dots, K_n)$$

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$$V_n(L_1, \dots, L_k, K_{k+1}, \dots, K_n) = \frac{1}{k!} \sum_{\epsilon \in \{0,1\}^k} (-1)^{k-|\epsilon|} V_n(L_\epsilon[k], K_{k+1}, \dots),$$

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- $V(K[n-1], [0, u], [0, v]) = \frac{1}{n(n-1)} \text{Vol}_2([0, u] + [0, v]) \text{Vol}_{n-2}(\pi_{(u,v)^\perp}(K))$ .

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- Continuity :  $\lim_k V_n(K_{1,k}, \dots, K_{n,k}) = V_n(K_1, \dots, K_n)$   
(if for each  $j = 1, 2, \dots, n$ ,  $K_{j,k} \rightarrow K_j$  as  $k \rightarrow \infty$ ).

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and  $h_K(u) = \max_{y \in K} \langle y, u \rangle$  is the support function of  $K$ .

Assume  $P$  is a polytope :  $P = \bigcap_{i=1}^N H^-(u_i, h_i)$ .

where  $H^-(u, b) := \{x \in \mathbb{R}^n : \langle x, u \rangle \leq b\}$

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Then for any convex body  $L$  :

$$V(L, P[n-1]) = \frac{1}{n} \sum_{i=1}^N h_L(u_i) \text{Vol}_{n-1}(P^{u_i})$$

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For any convex body  $K$ , there exists a (finite, non-negative) measure  $S_K$  on  $\mathbb{S}^{n-1}$ , such that :

$$\text{(for any } L), \quad V(L, K[n-1]) = \frac{1}{n} \int_{\mathbb{S}^{n-1}} h_L(u) dS_K(u).$$

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More generally, if  $K_1, \dots, K_{n-1}$  are convex bodies, then there exists a measure  $\sigma$  on  $\mathbb{S}^{n-1}$ , such that :

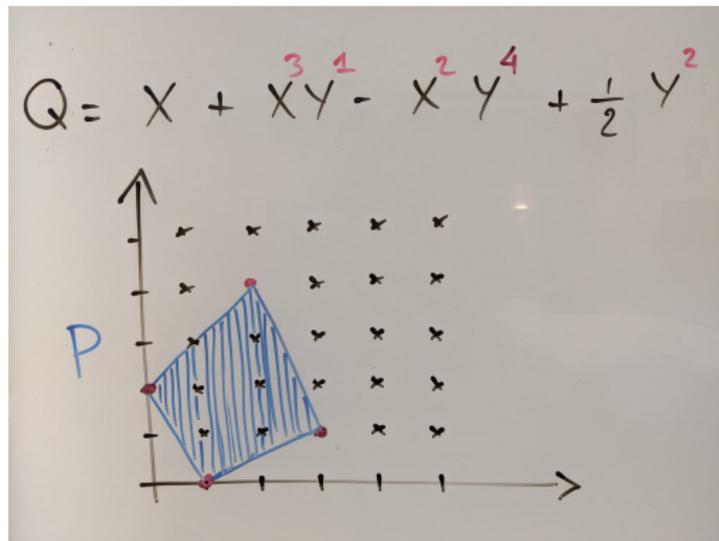
$$\text{(for any } L), \quad V(L, K_1, \dots, K_{n-1}) = \frac{1}{n} \int_{\mathbb{S}^{n-1}} h_L(u) d\sigma(u).$$

The measure  $\sigma$  is called a **mixed surface area measure**, and is usually denoted :

$$\sigma = S(K_1, \dots, K_{n-1}, \cdot)$$

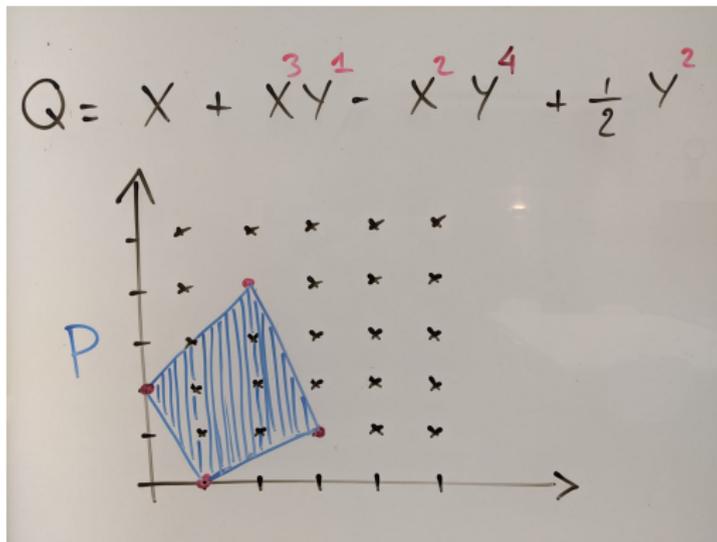
# Newton polytope of a polynomial

Let  $Q(X, Y) = \sum_{\alpha} c_{\alpha} X^{\alpha_1} Y^{\alpha_2} \in \mathbb{R}[X, Y]$ . Then the Newton polytope of  $Q$  is  $P = \text{Conv}\{(\alpha_1, \alpha_2) : c_{\alpha} \neq 0\}$ .



# Newton polytope of a polynomial

More generally, if  $Q \in \mathbb{R}[X_1, \dots, X_n]$ ,  $Q = \sum_{\alpha \in \mathbb{N}^n} c_\alpha X^\alpha$ ,  
then the Newton polytope of  $Q$  is  $P = \text{Conv}\{\alpha : c_\alpha \neq 0\} \subset \mathbb{R}_+^n$ .



Let  $f_1, \dots, f_r : \mathbb{R}^n \rightarrow \mathbb{R}$  be polynomials. Denote by  $X_1, \dots, X_r$  the associated algebraic varieties ( $X_i := \{x \in \mathbb{R}^n : f_i(x) = 0\}$ ).

The *Bezout inequality* states that :

$$\deg(X_1 \cap \dots \cap X_r) \leq \prod \deg(X_i) \quad [B]$$

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We can reformulate [B] within the language of mixed volumes :

$$V(P_1, \dots, P_r, \Delta[n-r])V(\Delta)^{r-1} \leq \prod_{i=1}^r V(P_i, \Delta[n-1])$$

thanks to a theorem by Bernstein, Kushnirenko and Khovanskii.

Let  $f_1, \dots, f_n : \mathbb{R}^n \rightarrow \mathbb{R}$  be polynomials.

Let  $X = X_2 \cap \dots \cap X_n$  of dimension 1, and  $Y = X_1$  (codim.1). Then Bezout inequality :

$$\deg(X \cap Y) \leq \deg(X)\deg(Y) \quad [B]$$

translates to

$$V_n(P_1, \dots, P_n)V_n(\Delta) \leq V_n(P_2, \dots, P_n, \Delta)V_n(P_1, \Delta[n-1]).$$

(recover previous inequality [B], by using [B]  $r - 1$  times)

$$V_n(L_1, \dots, L_n)V_n(\Delta) \leq V_n(L_2, \dots, L_n, \Delta)V_n(L_1, \Delta[n-1]).$$

Since the inequality is invariant under replacing  $L_1$  with  $\lambda L_1 + x$ , we may assume  $L_1 \subset \Delta$ , and  $r(\Delta, L_1) = 1$ , which implies  $h_{L_1}(u_j) = h_{\Delta}(u_j)$  for all outer normals  $u_j$ ,  $j \leq n+1$ , of  $\Delta$ .

- In this case :

$$V(L_1, \Delta[n-1]) = \frac{1}{n} \sum_{j=1}^{n+1} h_{L_1}(u_j) \text{Vol}_{n-1}(K^{u_j}) = V_n(\Delta)$$

- therefore [B] follows from monotonicity of mixed volume.

- Let  $K, L \in \mathcal{K}_n$ . The inradius of  $K$  relative to  $L$  is  $r(K, L) := \max\{\lambda > 0 : x + \lambda L \subset K, x \in \mathbb{R}^n\}$ .
- A corollary of Diskant's inequality :

$$r(K, L)^{-1} \leq n \frac{V_1(K, L)}{\text{Vol}(K)} = n \frac{V(K[n-1], L)}{\text{Vol}(K)}$$

- Using this, J. Xiao has shown (2019) :

$$V(L_1, \dots, L_n)V(K) \leq nV(L_2, \dots, L_n, K)V(L_1, K[n-1])$$

for any convex bodies  $L_1, \dots, L_n$ , and for any  $K$ .

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- $C = [0, 1]^n$  shows that  $n$  is sharp.

(to see that  $b(C) = n$ , take  $L_i = [0, e_i]$  and use projection formula).

- Let  $K, L \in \mathcal{K}_n$ . The inradius of  $K$  relative to  $L$  is  $r(K, L) := \max\{\lambda > 0 : x + \lambda L \subset K, x \in \mathbb{R}^n\}$ .
- Replace  $L_1$  with  $L' := r(K, L_1)L_1 + x \subset K$  ( $L'$  maximally contained).
- $r(K, L_1)V(L_1, \dots, L_n) = V(L', L_2, \dots, L_n) \leq V(K, L_2, \dots, L_n)$  (monotonicity)
- therefore :

$$\begin{aligned} V(L_1, \dots, L_n) &\leq r(K, L_1)^{-1} V(K, L_2, \dots, L_n) \\ &\leq \frac{nV(K[n-1], L_1)}{V_n(K)} V(K, L_2, \dots, L_n). \end{aligned}$$

We define :

$$b_2(K) = \max_{L_1, L_2} \frac{V(L_1, L_2, K[n-2])V(K)}{V(L_1, K[n-1])V(L_2, K[n-1])} \geq 1$$

And similarly

$$b(K) = \max_{L_1, \dots, L_n} \frac{V(L_1, \dots, L_n)V(K)}{V(L_2, \dots, L_n, K)V(L_1, K[n-1])} \geq 1$$

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So that :

- $b_2(\Delta) = b(\Delta) = 1$  (by BKK theorem, or directly with MV)
- $\forall K, 1 \leq b_2(K) \leq b(K)$  ;
- by [Diskant, Xiao] :  $\max_K b(K) \leq n$  .
- $\forall K, b(TK) = b(K)$ , for any (full-rank) affine  $T$ .

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# Who are the maximizers ?

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$\max_K b_2(K) \geq 2$  can be seen with  $K = O_n$  (the  $l_1$ -ball). Is there any better lower bound on  $\max_K b_2(K)$  ?

Question [Soprunov-Zvavitch 2015]

For which  $K$ , do we have  $b_2(K) = 1$ ?

→ recall  $b_2(K) = \max_{L_1, L_2} \frac{V(L_1, L_2, K[n-2])V(K)}{V(L_1, K[n-1])V(L_2, K[n-1])}$ .

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In words,  $b_2(K)$  is the least constant  $C > 0$  such that:

$$V(L_1, L_2, K[n-2])V(K) \leq C V(L_1, K[n-1])V(L_2, K[n-1])$$

holds for any  $L_1, L_2 \in \mathcal{K}_n$ .

Question [SZ '15]

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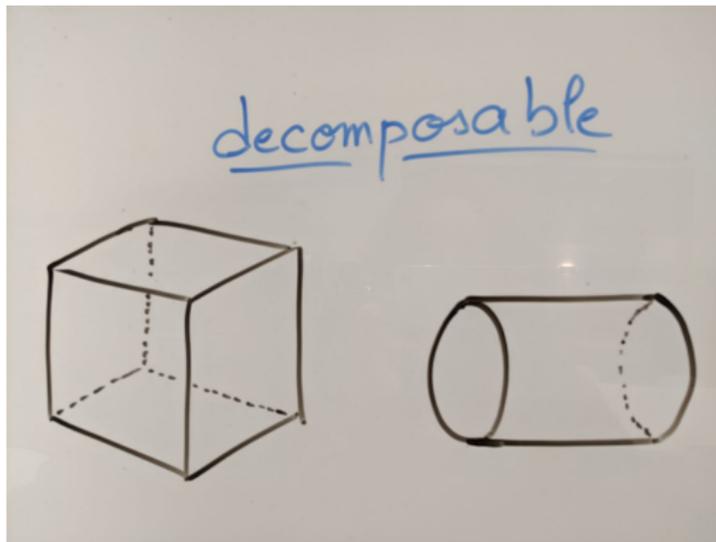
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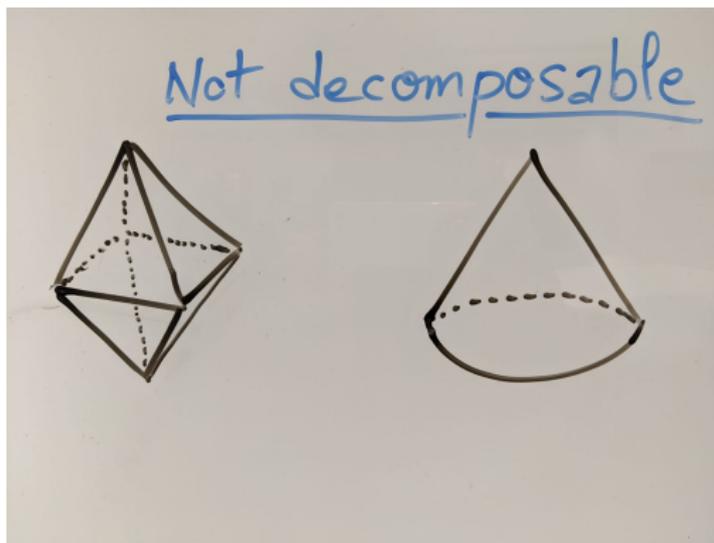
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Equality implies  $A$  and  $B$  are homothetic.

## Theorem[ SSZ '18]

Let  $P$  be an  $n$ -polytope. If  $b_2(P) = 1$ , then  $P = \Delta$ .

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Assume  $P = \bigcap_{i=1}^N H^-(u_i, h_i)$ , i.e.  $(h_i)$  is the support vector of  $P$ .

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Define  $P_{i,t} = \left( \bigcap_{j \neq i} H^-(u_j, h_j) \right) \cap H^-(u_i, h_i + t)$ , a perturbed version of  $P$ .  
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This cannot be the case for all facets  $P^{u_i}$  of  $P$ , unless  $P$  is a simplex.

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- A key feature in the proof of above Theorem :  $P + P_{i,t}$  has same outer normal vectors as  $P$ , if  $|t|$  is small.
- in other words :  $S_{P+P_{i,t}} \ll S_P$ , for  $t$  small.
- In general it is not true that  $S_{K+K_t} \ll S_K$ .

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(take  $L = A$ , then  $S_{K+L} = S_{2A+B}$  has same support as  $S_K$ ).

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- if  $K = A + B$  is decomposable, then it is weakly decomposable.
- if  $P$  is a polytope, and  $P \neq \Delta$ , then  $P$  is weakly decomposable.
- if  $\partial K$  is somewhere locally smooth, then  $K$  is weakly decomposable. ( $\rightarrow$  Wulff shape argument)

Open question : find a convex body  $K$  not weakly decomposable. ( $K \neq \Delta$ ).

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- recover the  $[b_2(P) = 1 \Rightarrow P = \Delta]$  theorem, since any  $P \neq \Delta$  is weakly decomposable.
- also recover the fact that decomposability is an *excluding condition*.
- Proof requires the notion of Wulff-shape perturbation.

## Definition

$K$  is called **weakly decomposable** if there exists  $L \in \mathcal{K}_n$ ,  $L \neq K$ , such that  $S_{K+L} \ll S_K$ .

## Theorem [SSZ'18]

If  $b_2(K) = 1$ , then  $K$  cannot be weakly decomposable.

- recover the  $[b_2(P) = 1 \Rightarrow P = \Delta]$  theorem, since any  $P \neq \Delta$  is weakly decomposable.
- also recover the fact that decomposability is an *excluding condition*.
- Proof requires the notion of Wulff-shape perturbation.

Open question : find a convex body  $K$  not weakly decomposable. ( $K \neq \Delta$ ).

Let  $K \in \mathcal{K}_n$ , and  $u \in \mathbb{S}^{n-1}$ . Recall that  $K^u = \{y \in K : \langle y, u \rangle = h_K(u)\}$ .

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Proposition [SZ'15], Prop 4.2 in [SSZ'18]

Assume there exists  $u \in \text{supp}(S_K)$ , such that  $K^u$  is 0-dimensional. Then  $b_2(K) > 1$ .

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Theorem [SSZ'18]

Assume  $K$  is a convex body with infinitely many facets. Then  $b_2(K) > 1$ .

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## A “dual” excluding condition

Let  $K \in \mathcal{K}_n$ , and  $u \in \mathbb{S}^{n-1}$ . Recall that  $K^u = \{y \in K : \langle y, u \rangle = h_K(u)\}$ . Denote  $\Omega := \text{supp}(S_K) \subset \mathbb{S}^{n-1}$ . Write  $\Omega = \bigcup_{d=0}^{n-1} \Omega_d$ , where  $\Omega_d = \{u \in \Omega : K^u \text{ is } d\text{-dimensional}\}$ .

Theorem [S. 2022+]

Assume  $S_K(\Omega_{n-2}) > 0$ . Then  $b_2(K) > 1$ .

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## Corollary

in  $\mathbb{R}^3$ , the simplex is the only minimizer of  $b_2(K)$ .

**Proof** (of corollary). Let  $K \in \mathcal{K}_3$ , write  $\text{supp}(S_K) =: \Omega =: \Omega_0 \cup \Omega_1 \cup \Omega_2$ . If  $\Omega_0 \neq \emptyset$ , then  $b_2(K) > 1$ , by [Prop. 4.2, SSZ'18]. Thus assume  $\Omega = \Omega_1 \cup \Omega_2$ .

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Note : this corollary was already known. It is proved in [SSZ'18].

Let  $L \in \mathcal{K}_n$  be a  $k$ -dimensional. Denote :

$$Iso(L) := \frac{1}{k} \frac{Vol_{k-1}(\partial L)}{Vol_k(L)} =: \frac{1}{k} \frac{|\partial L|}{|L|}$$

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By the isoperimetric inequality :

$$Iso(L) = \frac{1}{d} \frac{|\partial L|}{|L|} = \frac{1}{d} \frac{|\partial L|}{|L|^{\frac{d-1}{d}}} \frac{1}{|L|^{1/d}} \geq \frac{1}{d} \frac{|\partial B_2^d|}{|B_2^d|^{\frac{d-1}{d}}} \frac{1}{|L|^{1/d}} = \frac{|B_2^d|^{1/d}}{|L|^{1/d}}.$$

thus if  $(F_k)$  is a sequence of facets with  $Vol_{n-1}(F_k) \rightarrow 0$ , then  $Iso(F_k) \rightarrow +\infty$ .

Let  $L \in \mathcal{K}_n$  be a  $k$ -dimensional convex body. Denote :

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Theorem [S. 2022+]

If  $b_2(K) = 1$ , then, for any affine transform  $T$  :

For any facet  $F$  of  $K$  :  $Iso(TF) \leq Iso(TK)$ .

(since  $b_2(K)$  is affine invariant, while  $\max_F \frac{Iso(F)}{Iso(K)}$ , is not)

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- **Example** : the unit cube. It satisfies  $Iso(C_n) = 2$ , and so does any of its facets. Thus the criteria only allows to conclude  $b_2(C_n) > 1$ , after using an affine transform  $T$ .

**Question** : let  $P \neq \Delta$ . Does there necessarily exist  $T$  an affine transform, such that  $\max_F Iso(TF) > Iso(TP)$  ?

Thank you !!